IMPROVED SPEECH SPECTRAL VARIANCE ESTIMATION 
UNDER THE GENERALIZED GAMMA DISTRIBUTION

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ABSTRACT

DFT-based single-microphone speech enhancement methods need an estimate of the clean speech spectral variance. Often the "decision-directed" spectral variance estimator is used, because of its good performance: it strongly reduces the musical noise phenomenon. It has recently been shown that this estimator is severely biased at low SNRs when the smoothing factor approaches one [1]. Here we propose a variance estimator with reduced bias, under the assumption of a generalized Gamma distribution for the clean speech spectral amplitudes. For the reconstruction, the MMSE estimator of the amplitudes themselves is used, derived under the same distribution assumption. For the same speech quality versus noise reduction trade-off, the new variance estimator leads to less musicality.

1. INTRODUCTION

The traditional assumption for speech enhancement in the DFT domain is that the distribution of the complex speech DFT coefficients is Gaussian [2][3]. Consequently, the spectral amplitude distribution is modeled by a Rayleigh distribution. Recently, super-Gaussian models of the DFT coefficients have received quite some attention, because they lead to estimators with better performance than those based on a Gaussian model. Martin [4] derived complex-DFT estimators for Laplacian and Gamma speech priors, and Lotter and Vary [5] proposed a MAP amplitude estimator for a generalized Gamma amplitude distribution. MMSE estimators of the complex DFT coefficients, assuming a two-sided generalized Gamma distribution, have been derived in [6]. MMSE estimators for the amplitudes, assuming a one-sided generalized Gamma distribution, are treated in [7] and [8]. All these estimators need an estimate of the speech spectral variance, for which the "decision-directed" approach is commonly used [2].

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The decision-directed estimator contributes much to the good performance of the algorithms, because it strongly suppresses the musical noise [2][9]. However, when the smoothing parameter is very close to one, this estimator has undesirable convergence behavior at low SNRs, leading to over-suppression of the speech [1].

2. MMSE SPECTRAL ESTIMATION

2.1. Signal model and assumptions

We consider a signal model of the form

\[ X(k, n) = S(k, n) + D(k, n), \]

where \( X(k, n) \), \( S(k, n) \), and \( D(k, n) \) are complex-valued random variables representing the DFT coefficients obtained at frequency index \( k \) in signal frame \( n \) from the noisy speech, clean speech and noise process, respectively. Applying the standard assumption that \( S(k, n) \) and \( D(k, n) \) are statistically independent across time and frequency as well as from each other, it turns out that the expressions for the resulting estimators are independent of time and frequency. We drop the time and frequency indices whenever possible for ease of notation. We use capitals for random variables and the corresponding lowercase letters for their realizations. The speech amplitude is \( A = |S| \), and the noisy amplitude is \( R = |X| \). The noise DFT coefficients \( D \) are assumed to follow a complex Gaussian distribution with variance \( \lambda_D \).

Recent work [5]-[8] has shown that a generalized Gamma distribution assumption for the speech amplitudes can perform much better than the Rayleigh distribution assumption. This generalized Gamma distribution is given by

\[ f_A(a) = \frac{\gamma^{\beta\nu}}{\Gamma(\nu)} a^{\gamma\nu-1} \exp(-\beta a^\nu), \quad a \geq 0, \]

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with the constraints on the parameters $\gamma > 0$, $\nu > 0$. We will consider the cases $\gamma = 1$ and $\gamma = 2$. Because $E\{A^2\}$ equals $\lambda_S$ by definition, $\beta$ is related to $\nu$ and $\lambda_S$. For $\gamma = 1$ we have $\beta^2 = \nu(\nu + 1)/\lambda_S$, while $\beta = \nu/\lambda_S$ for $\gamma = 2$. For $\gamma = 2$, the Rayleigh distribution appears as a special case of (2) when $\nu = 1$.

2.2. Amplitude estimators for the generalized Gamma model

The MMSE estimator of some power $p$ of the speech amplitude is (see, e.g., [10]):

$$\hat{A}^p = E\{A^p|R\} = \frac{\int_0^\infty a^p \exp(-\frac{a^2}{\lambda_S}) I_0(\frac{2aR}{\lambda_S}) f_A(a) da}{\int_0^\infty \exp(-\frac{a^2}{\lambda_S}) I_0(\frac{2aR}{\lambda_S}) f_A(a) da},$$

(3)

where $I_0(\cdot)$ is the zeroth order Bessel function of the first kind. $\hat{A}^p$ is called the $p$-th order amplitude estimator. MMSE estimators are unbiased [11]. In particular, the expectation of $\hat{A}^2$ w.r.t. the distribution of $R$ equals the speech spectral variance $\lambda_S$, i.e., $\int_0^\infty \hat{A}^2(r) f_R(r)dr = \lambda_S$. This property will be used in section 3 to improve the spectral variance estimation.

2.2.1. First and second order estimators

MMSE amplitude estimators for the distribution classes $\gamma = 1$ and $\gamma = 2$ have been derived in [8]. For $\gamma = 2$ the derivation is exact, see also [7]. For the case $\gamma = 1$ accurate analytical approximations to the exact MMSE estimators can be made for $\nu > 0.5$ [8]. The maximum achievable performance for both classes is about the same. Due to space limitations, we show only the expressions for the estimators of the $\gamma = 2$ class for which the Gaussian speech model occurs as a special case for $\nu = 1$. For $p = 1$, the estimator is

$$\hat{A}^{(2)} = \frac{\Gamma(\nu + 0.5)}{\Gamma(\nu)} \sqrt{\frac{\xi}{\xi + \nu}} \frac{1}{F_1(\nu + 0.5; 1; \frac{\xi + \nu}{\nu})} R,$$

(4)

with the $\nu$-dependency explicitly indicated. The superscript (2) indicates that $\gamma = 2$. $F_1(a; b; x)$ is a confluent hypergeometric function [12, 13.1.2], $\xi = R^2/\lambda_D$ is the a posteriori SNR, and $\xi = \lambda_S/\lambda_D$ is the a priori SNR. For $p = 2$, we arrive at

$$\hat{A}^{(2)} = \frac{\nu \xi}{\xi + \nu} \frac{1}{F_1(\nu + 1; 1; \frac{\xi + \nu}{\nu + \xi})} R^2.$$

(5)

For large arguments of the convergent hypergeometric function, and finite $\nu$, (4) and (5) converge to $\xi R/(\nu + \xi)$ and $(\xi R)^2/(\nu + \xi)^2$, respectively [12, 13.5.1].

3. A PRIORI SNR ESTIMATION

3.1. Conventional decision-directed estimator

The a priori SNR has to be estimated and a common approach is the “decision-directed” method [2]:

$$\hat{\xi}_1(n) = \max \left[ \frac{\alpha \hat{A}^2(n-1) + (1 - \alpha)\xi(n-1)}{\lambda_D(n)}, \xi_{\text{min}} \right],$$

(6)

where the subscript 1 refers to the use of the first order amplitude estimator $\hat{A}(n-1)$ of the previous time frame. It can be shown that (6) is biased low at low SNRs [1]. The bias propagates in time, affecting future realizations of $\hat{A}$ and $\xi$ and causing the latter to converge to $\xi_{\text{min}}$ in stationary signals for $\alpha \rightarrow 1$, thereby causing too much suppression of weak speech components. This explains why at low SNRs, the estimated a priori SNR is a highly smoothed version of the observed a posteriori SNR, as was found experimentally by Cappé [9]. For low values of $\alpha$, the second term $(1 - \alpha)[\xi - 1]$ becomes the most important. This term is unbiased, but has a large variance, causing the residual noise to sound musical [9]. The reason for the bias in (6) for $\alpha$ near one is the following. An MMSE amplitude estimator is a conditional expectation. Its square is used in (6). It is well-known (Jensen’s inequality) that the square of an expectation is less than or equal to the expectation of the square. The expectation of the second order MMSE amplitude estimator equals $\lambda_S$. Therefore, the expectation of the square of the first order amplitude estimator is smaller than the spectral variance.

3.2. Bias-corrected estimator

The above reasoning suggests to use instead in (6) the second order amplitude estimator (i.e., (3) with $p = 2$), leading to:

$$\hat{\xi}_2(n) = \max \left[ \frac{\alpha \hat{A}^2(n-1) + (1 - \alpha)[\xi(n-1) - 1]}{\lambda_D(n)}, \xi_{\text{min}} \right].$$

(7)

However, $\sqrt{\hat{A}^2}$ is not used also for amplitude reconstruction, because it is not the MMSE first order amplitude estimator. We compute both the amplitude and second order amplitude estimates for the same prior distribution (2). The second order amplitude estimate is used only for a priori SNR estimation, while the amplitude estimate is used only for the speech reconstruction. Note that the bias correction makes it possible to use $\alpha = 1$ in (7), without very severe speech distortions, in contrast to (6). It can be shown that for $\nu \rightarrow \infty$, the first and second order amplitude estimates approach $\sqrt{\lambda_S}$ and $\lambda_S$, respectively,
where $\lambda_S = \hat{\xi}_D$. This is also true for the $\gamma = 1$ case. The reason for this behavior is that for $\nu \to \infty$, (2) tends to a delta-function centered around $\sqrt{\lambda_S}$ for a given $\lambda_S$. Consequently, both decision-directed \textit{a priori} SNR estimators (6) and (7) behave like an ordinary exponential smoother for $\nu \to \infty$, resulting in a very reverberant character of the enhanced speech, without any musicality. Of course, these estimators are also identical for $\alpha = 0$.

We will show that the use of (7) leads to a better perceptual quality than the use of (6) for a proper choice of the parameters $\nu$ and $\alpha$.

### 4. EXPERIMENTAL RESULTS

#### 4.1. Experimental set-up

In the enhancement system, we use 50%-overlapping frames of 32 ms (256 samples at 8 kHz sampling frequency). The data window used was a cosine-squared window. We use all 30 clean sentences of the NOIZEUS database [13]. Noisy signals were generated by adding white and nearly stationary car noise from the Noisex-92 database [14] to the clean signals, at 5 and 15 dB overall SNR. The noise was limited to telephone bandwidth (300-3400 Hz). The noise spectral variance was estimated from 0.64 seconds of noise only, preceding speech activity. Objective quality was measured in two different ways. We measure mean-square error ($MSE$), because it is the quantity that MMSE estimators should minimize on average. We compute $MSE$ as

$$ MSE = \frac{1}{N} \sum_{n=1}^{N} \sum_{k} (a(k, n) - \hat{a}(k, n))^2, \quad (8) $$

where $a(k, n)$ and $\hat{a}(k, n)$ are the clean speech spectral amplitude and the estimated amplitude of frequency bin $k$ and time frame $n$, and $N$ is the number of frames in a speech sentence. To exclude silence intervals, frames with a clean energy more than 40 dB below the maximum clean frame energy of a speech sentence are not taken into account. All results at a given SNR are averages over all test sentences. Furthermore, to quantify the speech distortion versus noise reduction trade-off, we also measure separately segmental Speech Quality ($SQ$) and Noise Reduction ($NR$) as in [5], and plot these quantities against each other while varying $\nu$.

#### 4.2. Performance evaluation

We evaluated the estimators for both the $\gamma = 1$ and $\gamma = 2$ classes. For each class, we compared the results of using either (6) or (7) for a \textit{a priori} SNR estimation. Figures 1 and 2 compare the standard \textit{a priori} SNR estimator (6) with the corrected one (7), for $\gamma = 1$ and $\gamma = 2$, respectively. We used $\alpha = 0.98$ and $\xi_{\text{min}} = -19$ dB. For a proper choice of $\nu$, about a 10% lower MSE is possible with (7) than with (6). With (6), for $\gamma = 1$, larger noise reductions are obtained for a given $\nu$, but the maximum achievable speech quality is lower.

It is possible to increase $SQ$ (and decrease $MSE$) for (6), by lowering the value of $\alpha$. This will decrease $NR$ and increase the musicality. The question arises whether the gain in objective quality shown for (7) comes at the cost of an increase in musicality. We have found that this is not the case from the following experiment. The quality measures considered are influenced by both parameters $\nu$ and $\alpha$. We evaluated the estimators for a wide range of values. We used fifteen values of $\alpha$ between 0 and 1 and eleven values of $\nu$ between 0.01 and 4 for $\gamma = 2$, and between 0.51 and 4.5 for $\gamma = 1$. Figure 3 shows scatter plots of $SQ$ versus $NR$ for all values of $\nu$ and $\alpha$, for $\gamma = 2$, white noise at (a) 5 dB and (b) 15 dB SNR. The dots are for (6) and the pluses for (7). The dots at low $SQ$ that are separated from the main cluster correspond to $\alpha = 1$ in.

![Figure 1](image1.png)

Figure 1: $MSE$ versus $\nu$ and Speech Quality versus Noise Reduction for $\gamma = 1$ for the standard \textit{a priori} SNR estimator (6) and the corrected one (7). White and car noise have been used at overall SNRs of 5 and 15 dB.

![Figure 2](image2.png)

Figure 2: As Figure 1, but for $\gamma = 2$. 

![Figure 3](image3.png)
Figure 3: SQ versus NR for $\gamma = 2$. White noise has been used at overall SNRs of (a) 5 dB and (b) 15 dB.

6. REFERENCES


